



# Designing for Acceleration: Methodologies for Creating Reconfigurable Applications

Presented By

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# Topics

- > **Partial Reconfiguration Technology Review**
- > **SDAccel and Dynamic Platforms**
- > **Future Enhancements**



# Partial Reconfiguration Silicon and Software Technology



# Partial Reconfiguration is mainstream

## > In production since 2010

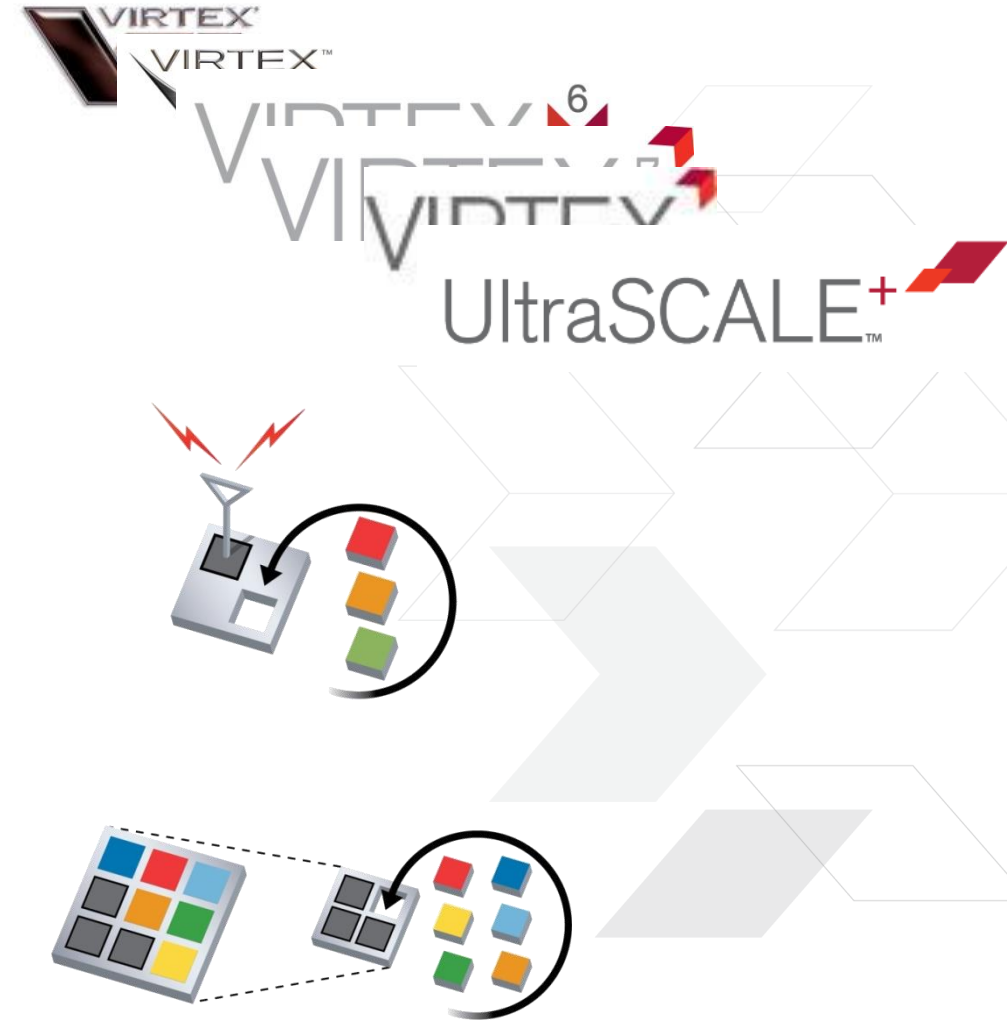
- >> Starting with Virtex-4, through UltraScale+
- >> Continuous silicon improvements with each generation
- >> Major advancement with the introduction of Vivado

## > System Flexibility

- >> Swap functions on the fly
- >> Enables hardware acceleration platforms
- >> Perform remote updates while system is operational

## > Cost and Size Reduction

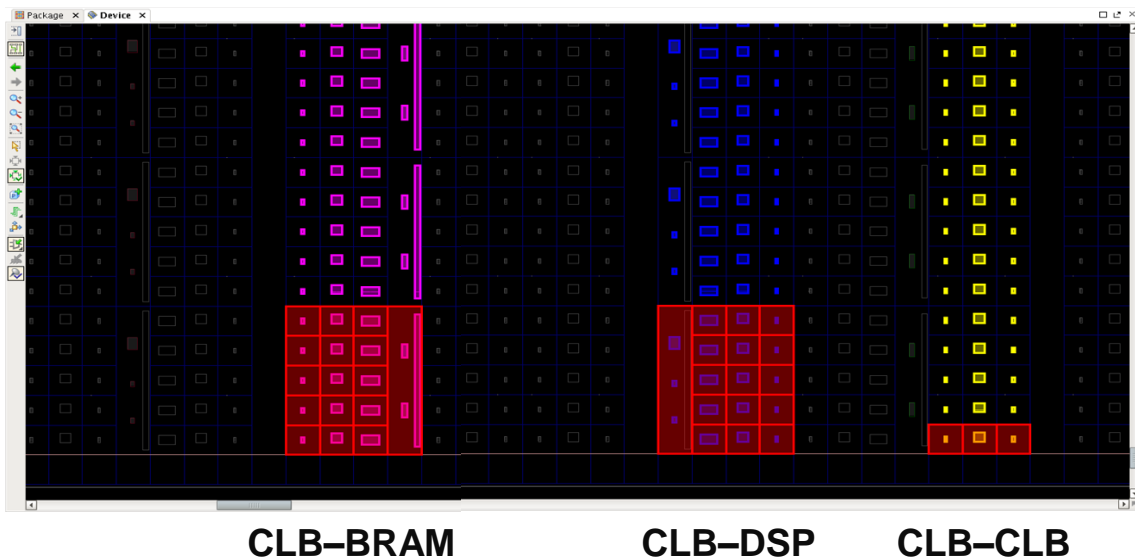
- >> Time-multiplexing hardware requires a smaller FPGA
- >> Reduces board space
- >> Minimizes bitstream storage



# Reconfigurable granularity in UltraScale/+

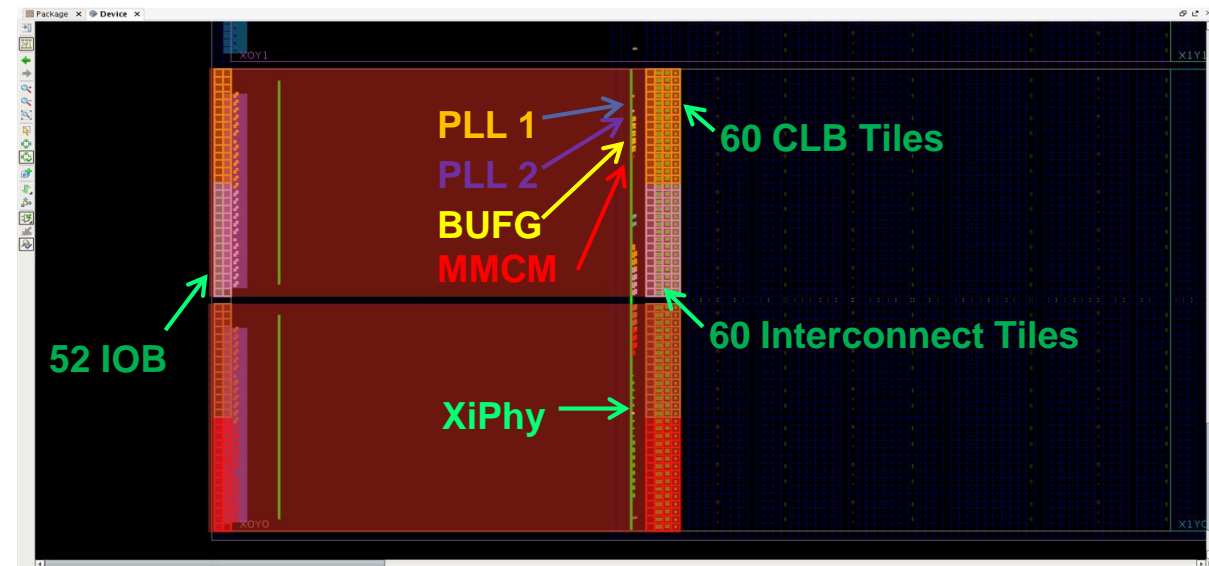
## > Reconfiguration tiles for core fabric based on shared interconnect

- >> Base regions combined two columns of resources with single INT
- >> Bitstream granularity is larger, matching clock region height



## > IO and special elements have coarser rules, shared with column of CLBs

- >> IO and clocks: 1 bank
- >> Transceivers: 1 quad
- >> PCIe, CMAC, Interlaken: 1 clock region



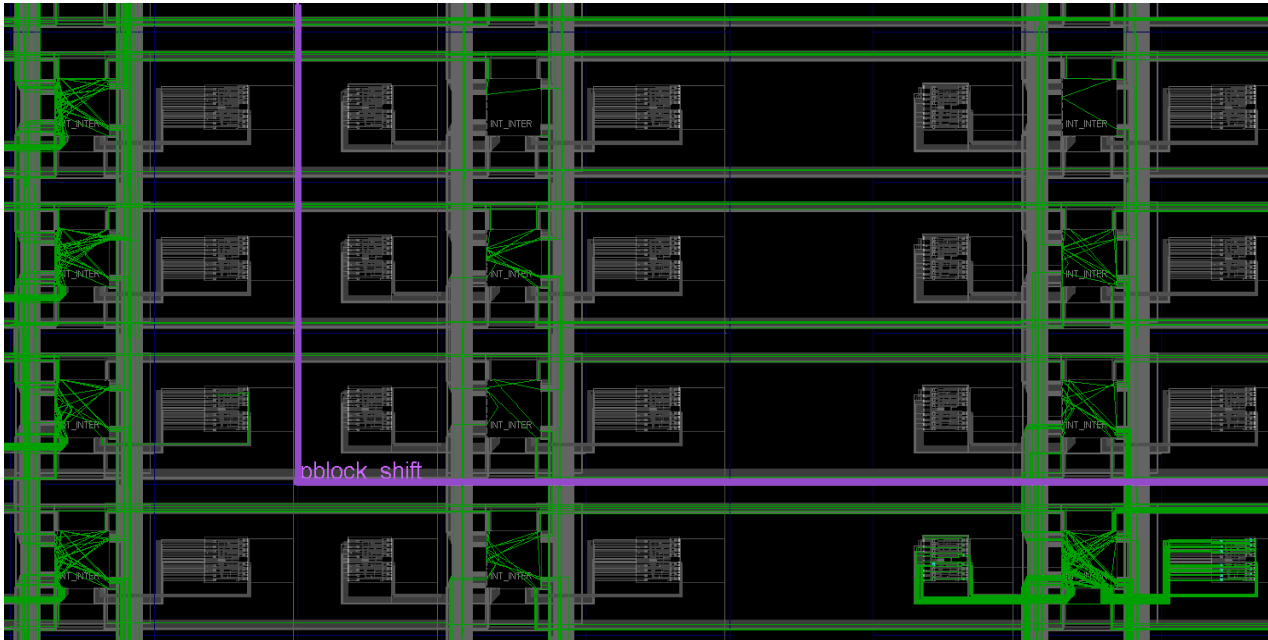
# Dedicated silicon features provide design safety

- > **Dedicated initialization for reconfigured regions**
  - >> Reconfigured region is masked and receives GSR for all synchronous elements in partial bitstream
  - >> Behaves just like the initial configuration of the device
- > **Encryption and Compression natively supported**
  - >> Authentication is also supported for Zynq SoCs
- > **CRC checking for partial bitstreams**
  - >> Standard single CRC at the end of a partial bitstream can report errors
  - >> Per-frame CRC feature injects CRC checks at intervals in partial bitstream
    - Failures are found and reported before bad frames are loaded into the device

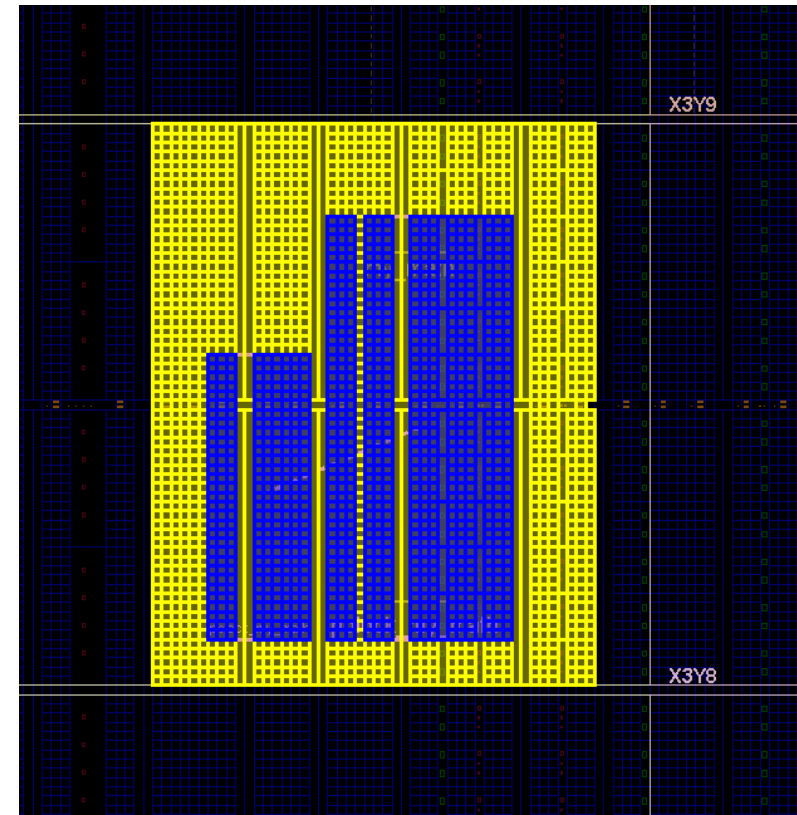


# Glitchless transitions and routing flexibility

- > **Static routes pass through reconfigurable regions without disruption**
  - >> Routing structure and global controls designed for glitchless static operation



- > **Expanded routing regions provide solution flexibility**
  - >> Alleviates congestion near corners and edges



# Capable Vivado toolset for compilation

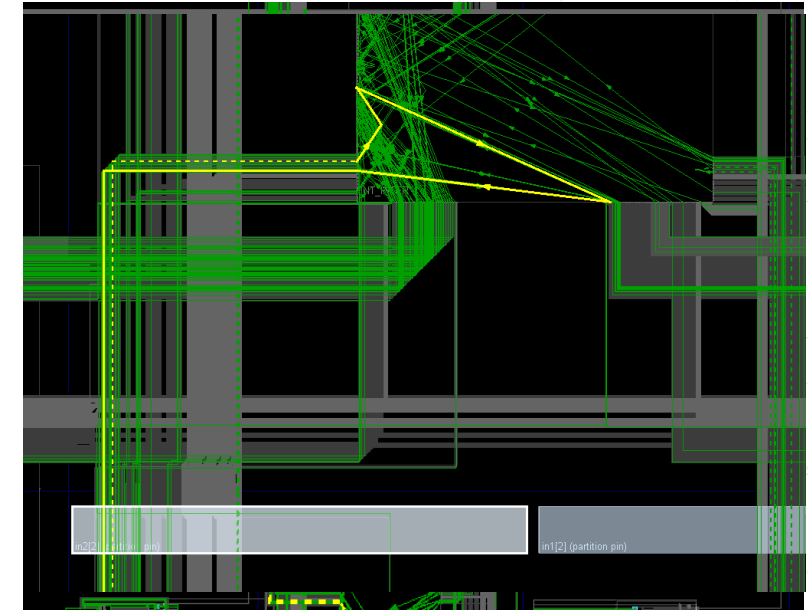
## > Major software overhaul for PR completed in 2013

>> PR included in all paid editions and kits since 2017

## > Technology improvements for performance and efficiency

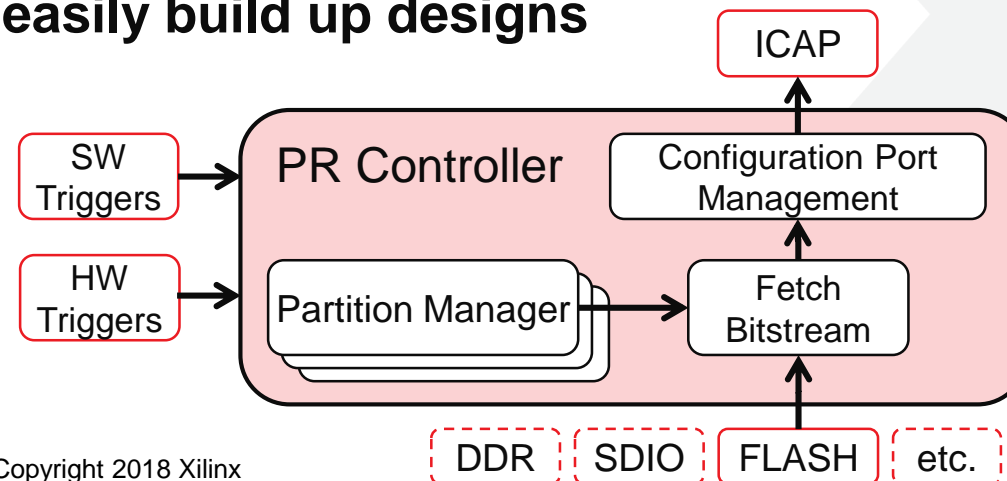
>> Example: Partition Pins

- No overhead between static and dynamic logic
- Vivado optimized location and distribution



## > Partial Reconfiguration IP helps users easily build up designs

- >> Partial bitstream delivery management
- >> AXI transitional behavior
- >> Logical isolation
- >> Version compatibility

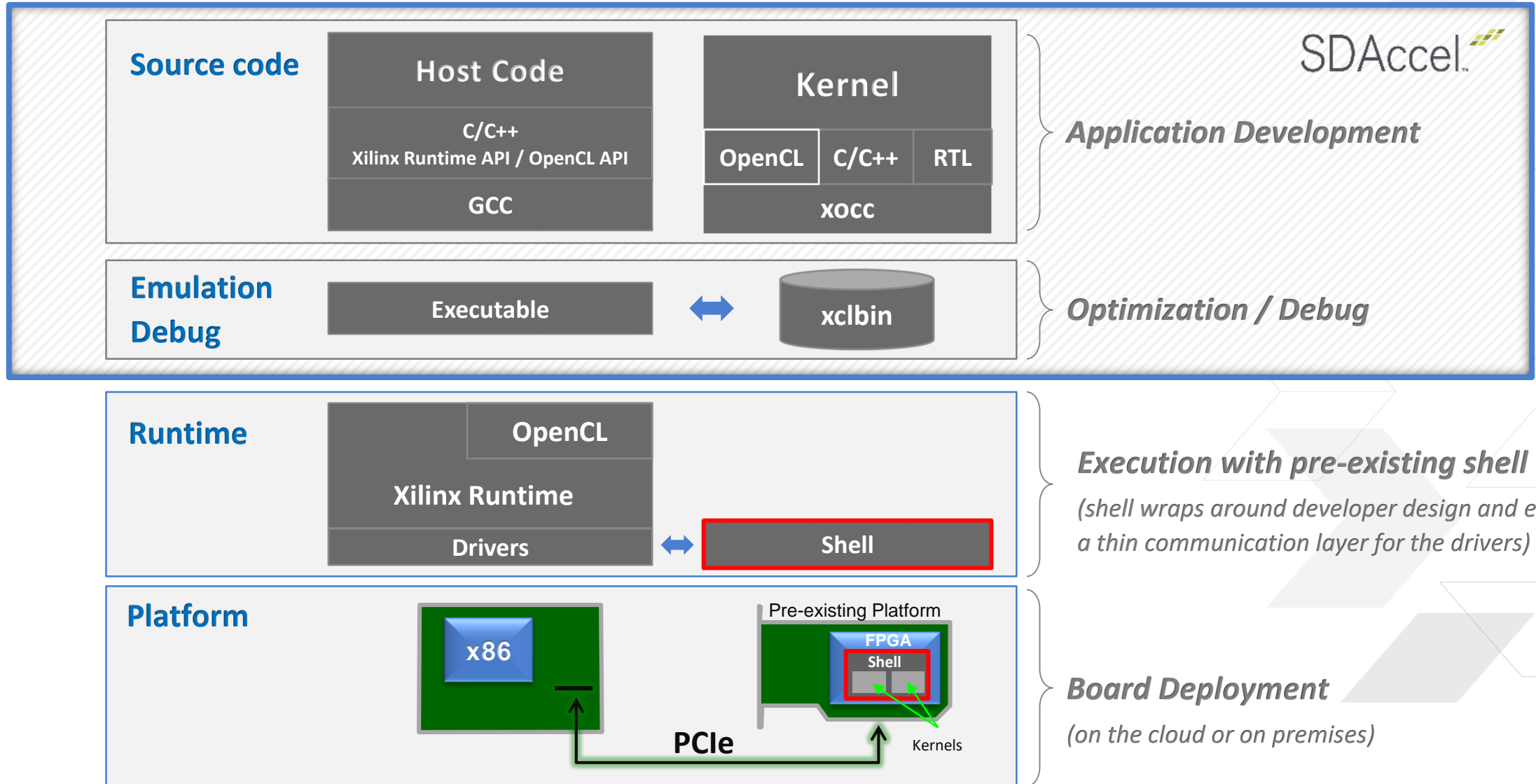




# Evolution of SDAccel Acceleration Platforms



# SDAccel software development environment

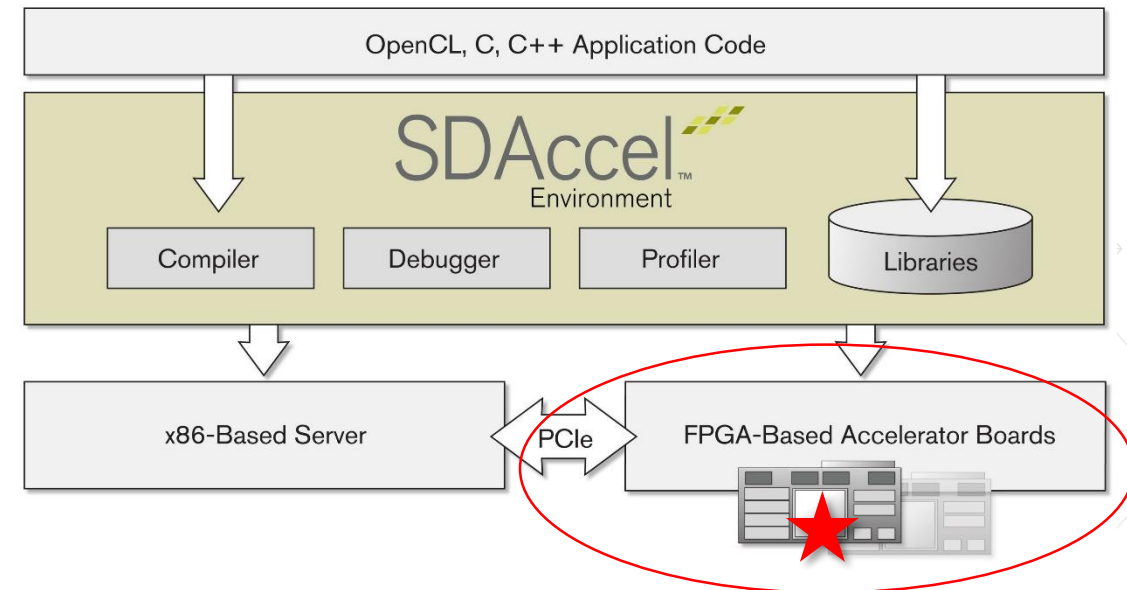


# What is a platform?

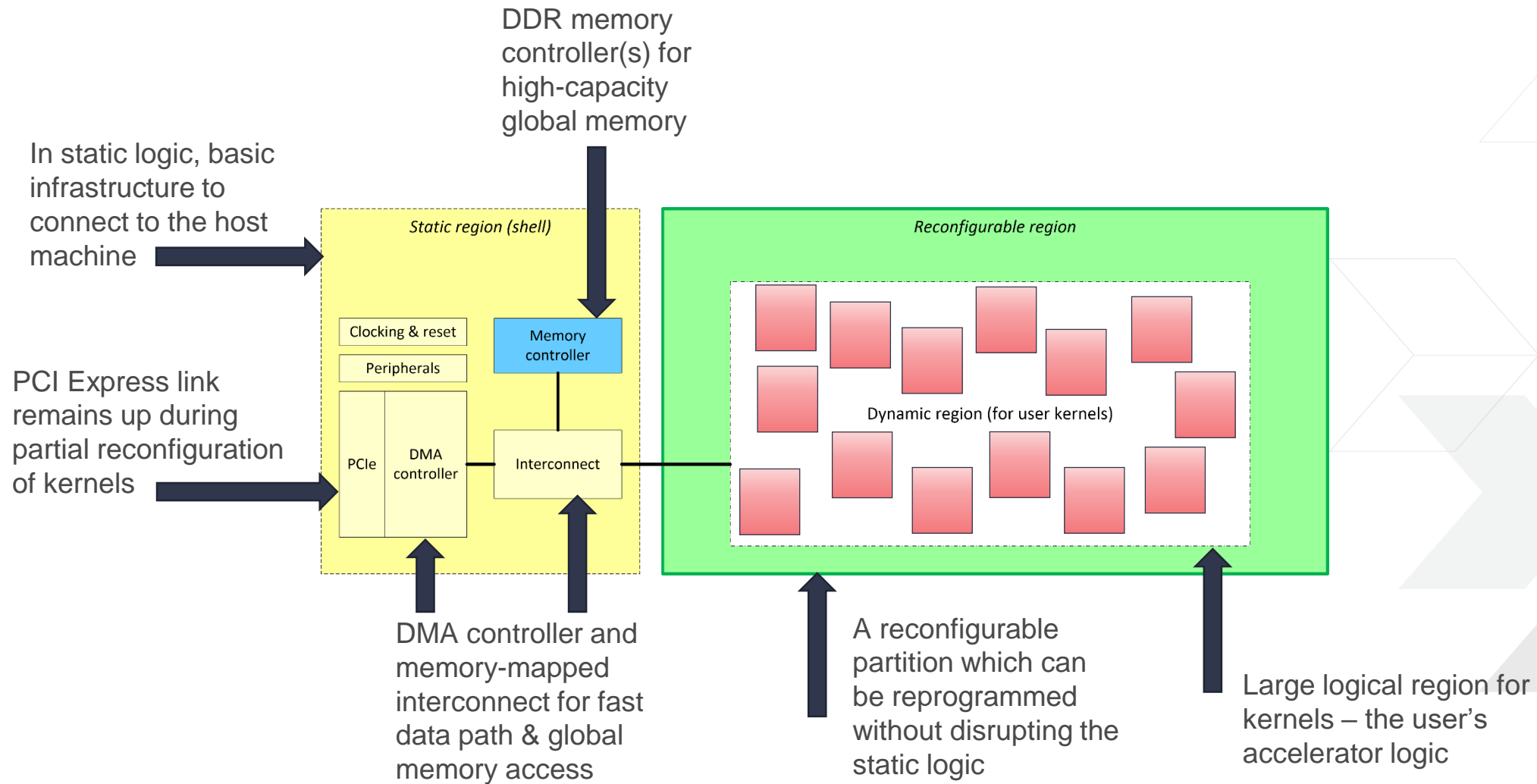
- > **A platform is the hardware design which operates on an accelerator board's FPGA to enable integration of the board and host computer with the user's accelerator (kernel) logic**
  - >> Think "Device Support Archive", not *just* its "shell"
- > **Examples of platform content:**
  - >> Persistent PCI Express link to the host computer
  - >> DMA controller and interconnect for fast memory access
  - >> Memory controllers for DDR4 SDRAM global memory
  - >> Security and board management features
  - >> A Partial Reconfiguration-enabled design and floorplan
- > **In most acceleration platforms, a small static region (shell) provides this core functionality while a large reconfigurable region is available for user kernels**
  - >> The platform also implements the bridging between the two regions

## SDAccel™ Development Environment

CPU/GPU-Like Development Experience on FPGAs



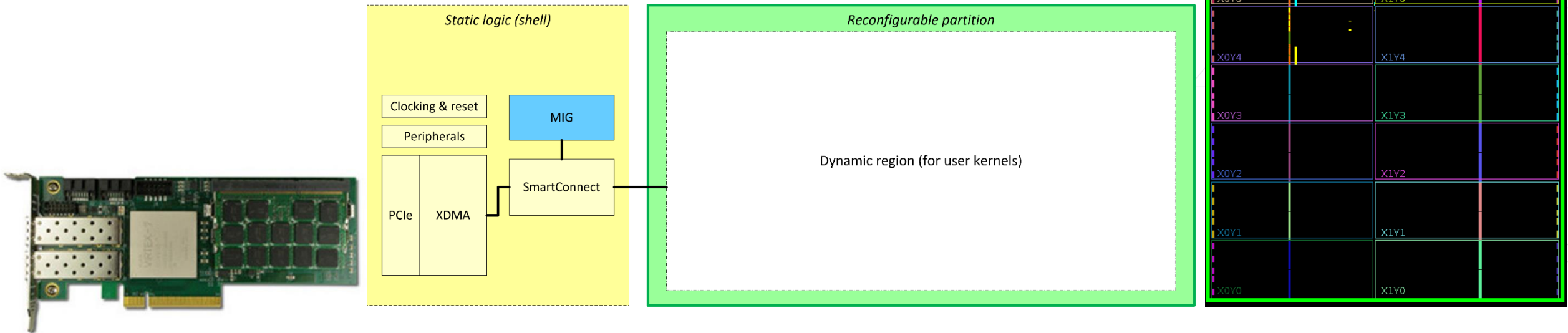
# Block diagram of a prototypical platform



# Where it started

## Virtex-7 690T platform with Partial Reconfiguration

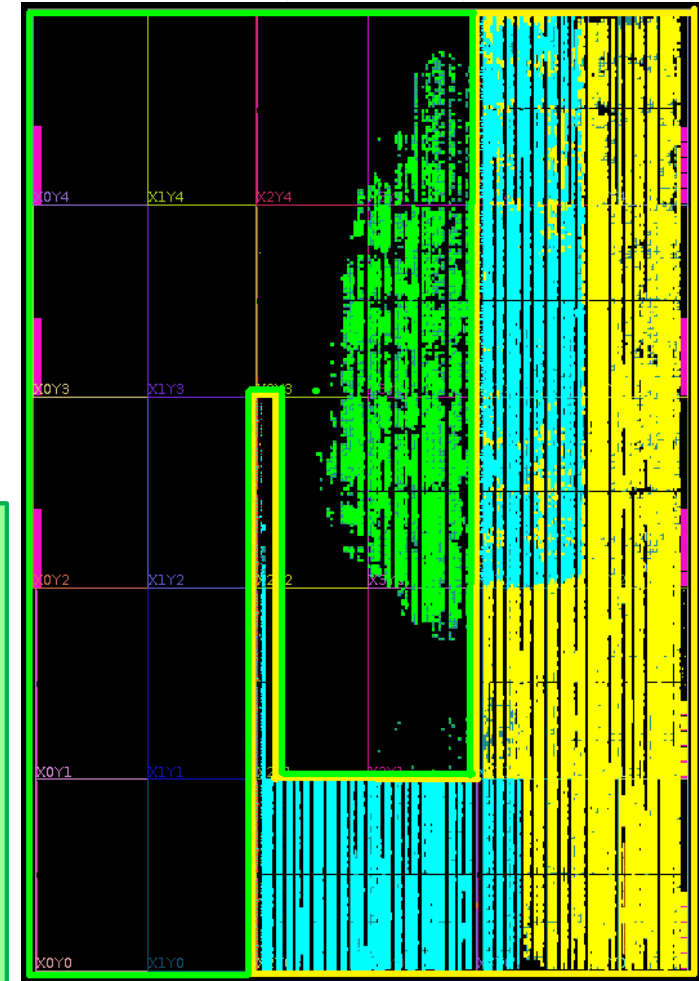
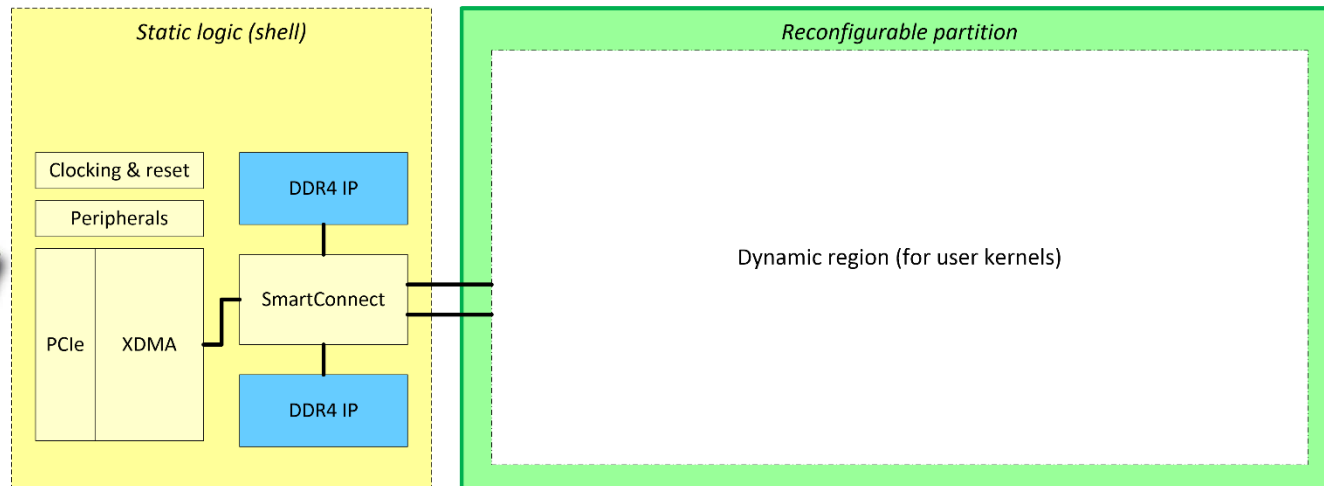
- > Natural static/PR partitioning and simple device floorplan
- > Relatively large rectangular dynamic region
- > Single memory controller in the shell
- > A good starting point, but not much bandwidth



# The first UltraScale platform

## Kintex UltraScale KU060 platform with Partial Reconfiguration

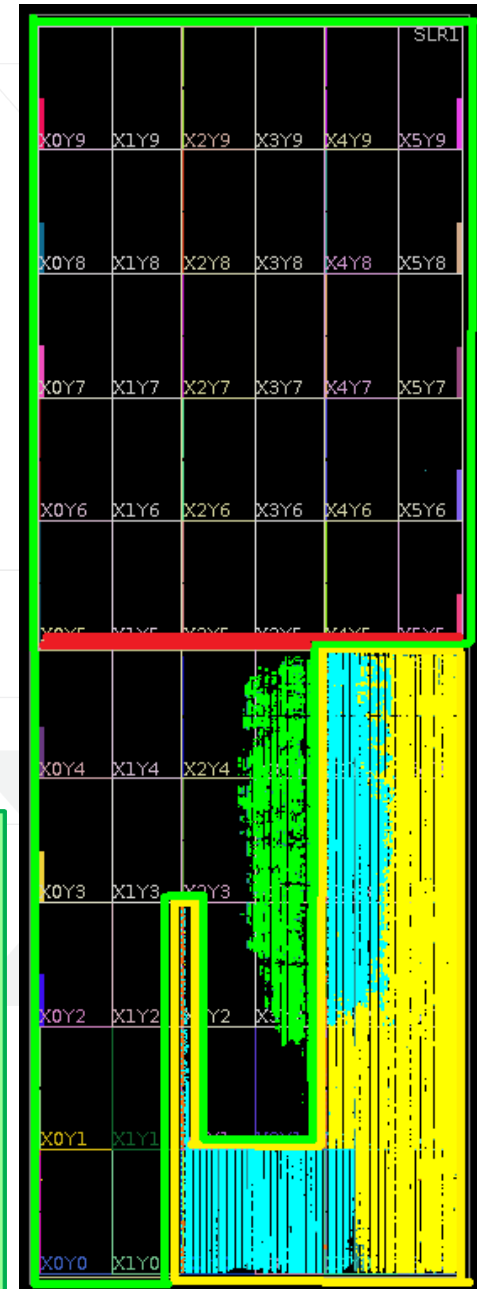
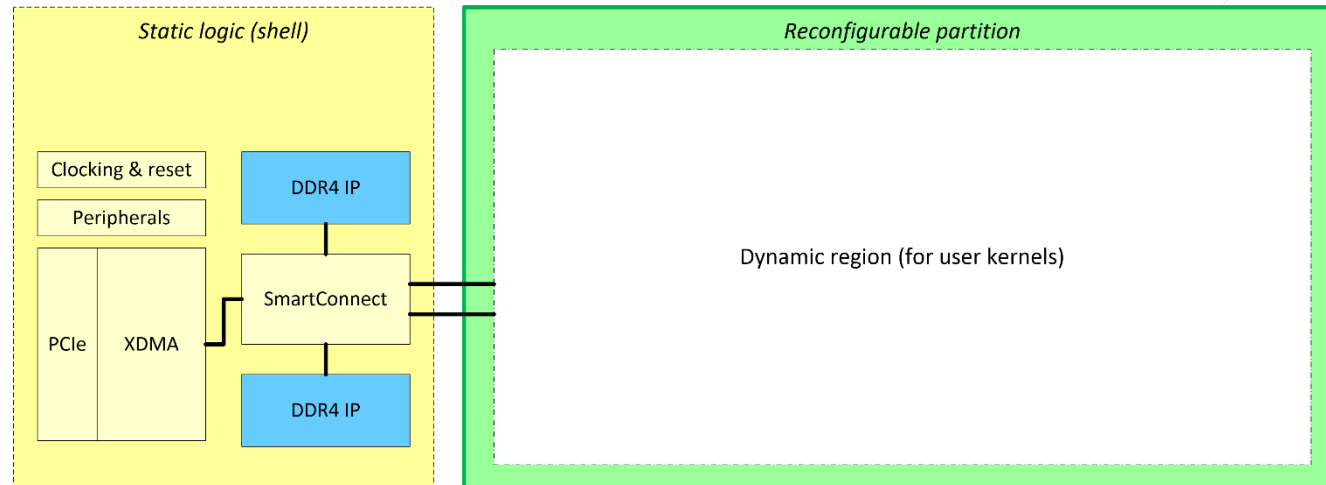
- > Second memory controller and DDR4 for more bandwidth
- > But awkward memory controller locations
- > Shell is relatively large for the device



# Larger SSI device, same shell

## Kintex UltraScale KU115 platform with Partial Reconfiguration

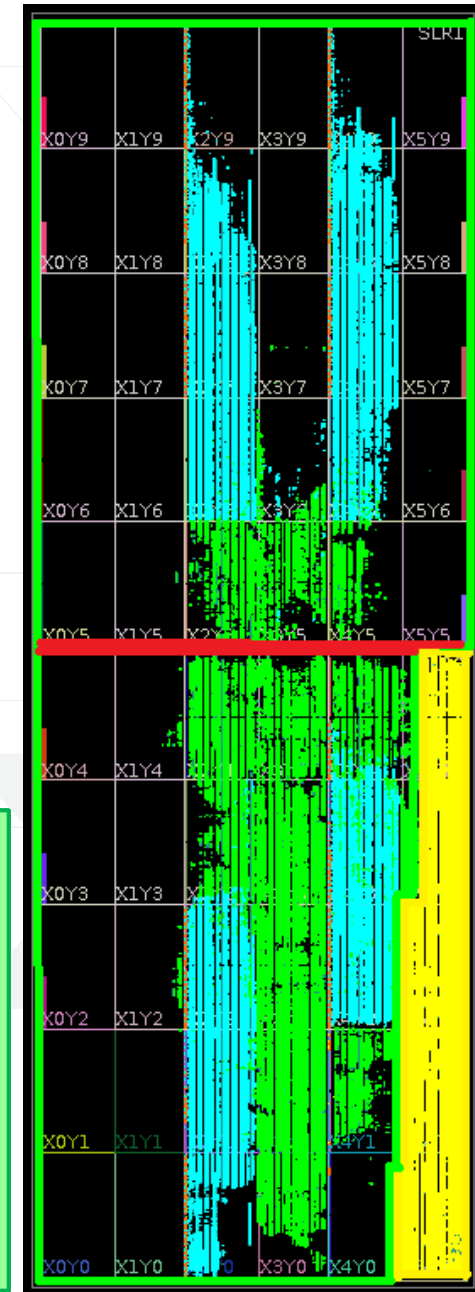
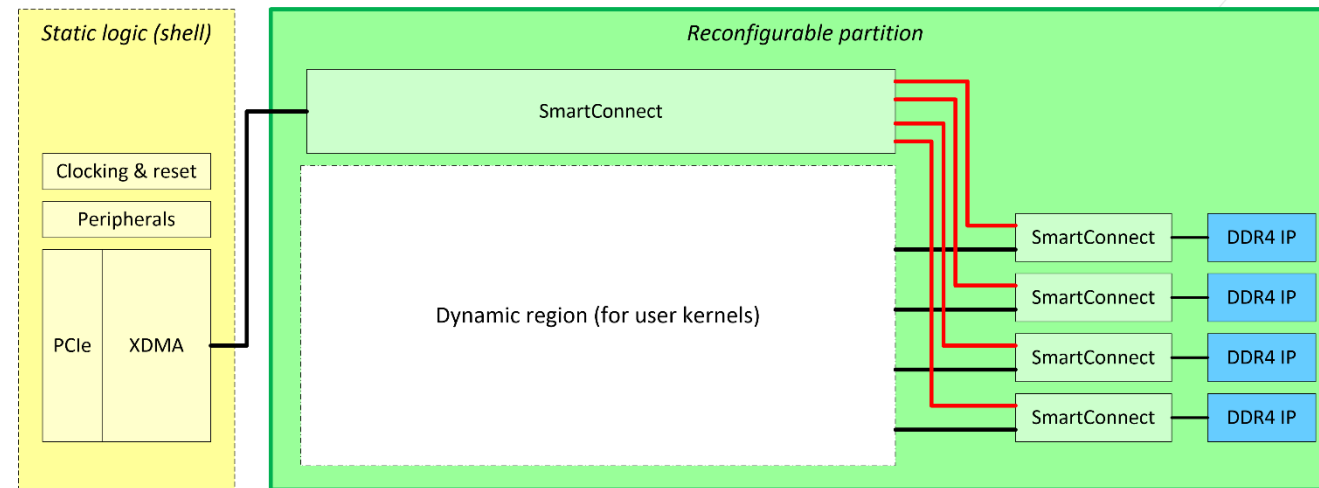
- > Almost the same platform as the KU060 variant, on larger device
- > Second SLR offered >2x the available area for kernels
- > But unmanaged SLR crossings proved problematic
- > Still 2 DDR4 channels, despite enough HPIO banks for 4 channels



# A new kind of platform

## Kintex UltraScale KU115 platform with *Expanded PR*

- > First Xilinx-built board for SDAccel
- > Four DDR4 memory controllers for 2x bandwidth
- > ... but no good floorplan with the standard platform approach
- > Adopted a new approach: *Expanded Partial Reconfiguration*
  - >> Static shell is much smaller
  - >> Distributed interconnect better manages SLR crossings
  - >> Dynamic region for kernels now a subset of the reconfigurable module

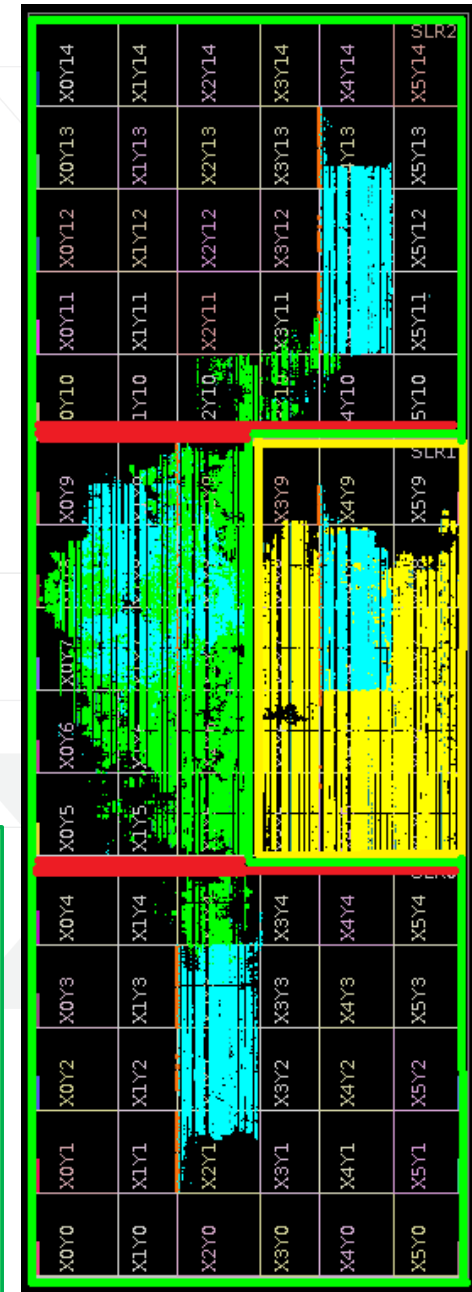
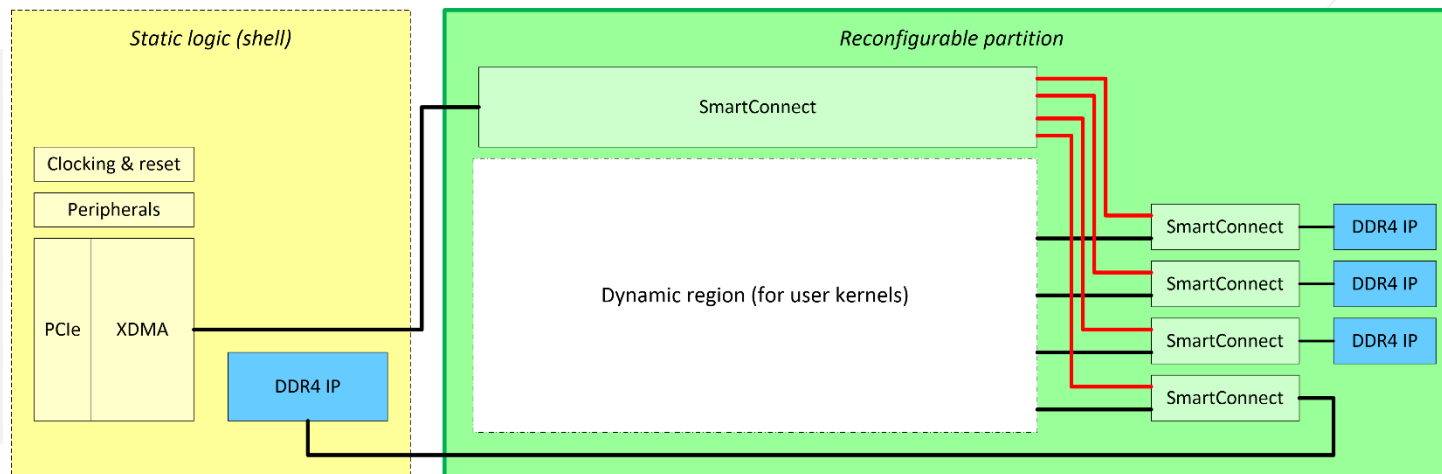




# Pushing the limits

## Virtex UltraScale+ VU9P platform with Expanded PR

- > Same approach as in KU115-based expanded PR platform
- > Now with 3 SLRs and more interconnect logic
- > But several inefficiencies becoming more prominent
  - >> Just too much static logic for simple use cases
  - >> Automatic placement of kernels sometimes inconsistent with manually-placed platform infrastructure
  - >> Still no variability of platform contents ... DIMMs?, debug IP?, etc.

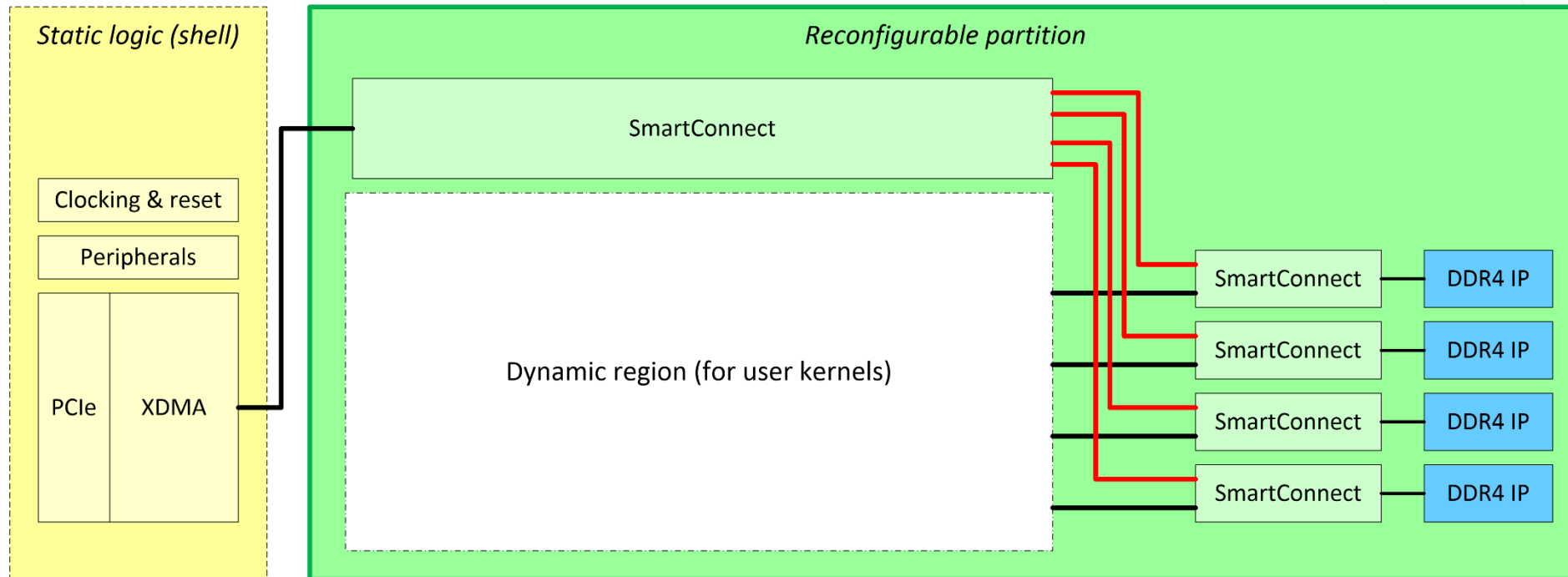


# The reality

- > **VU9P platform with Expanded Partial Reconfiguration is a powerful, full-featured platform**
- > **And maybe it is perfect for the user**
  - >> Exactly the right number of DDR4 memory channels vs. free fabric resources
  - >> Just the right performance tuning
  - >> Works perfectly with user kernels (no debug necessary)
  - >> Performance profiling taps are in the right places
  - >> Ideal logic placement for kernels relative to platform interconnect
- > **But if not...**
  - >> For a different number of DDR4 channels: **new platform**
  - >> For different performance tuning / memory parameters: **new platform**
  - >> Any issues requiring debug IP inserted at the problematic location: **new platform**
  - >> Modified performance profiling tap points: **new platform**
  - >> Different interconnect topology or for required kernel placement: **new platform**

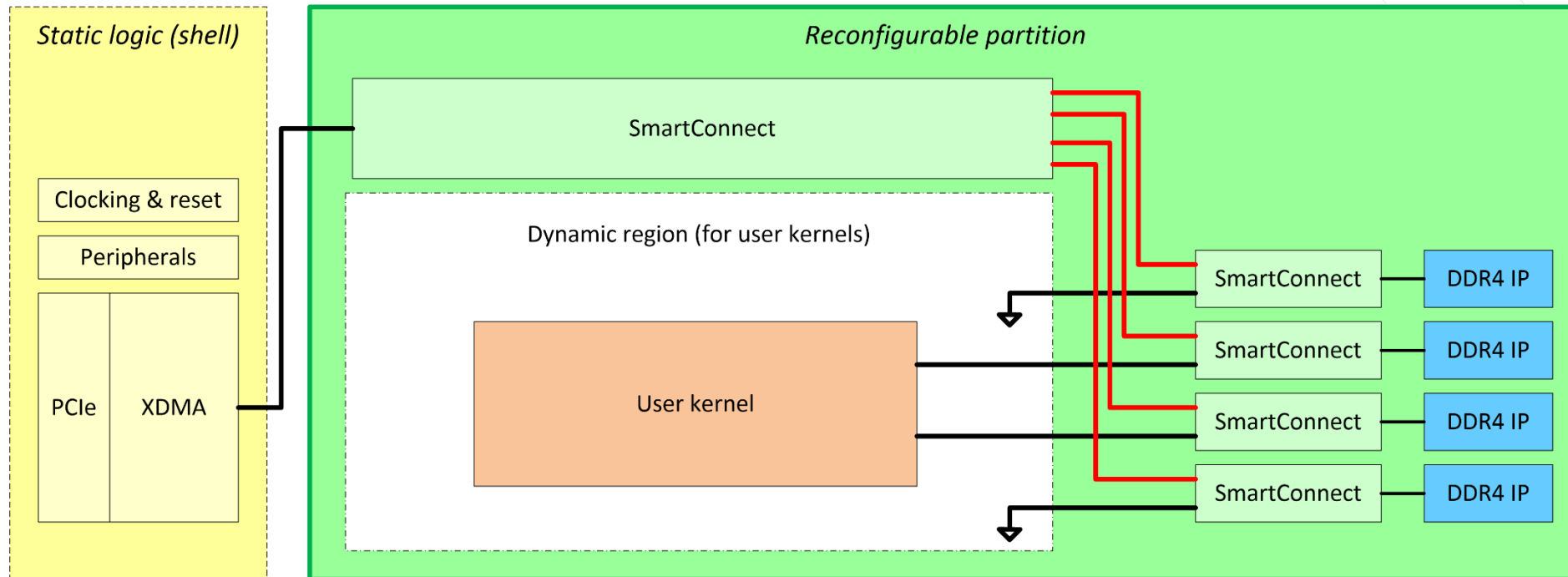
# A better way

- > Platform logic in the reconfigurable module was fixed for every kernel build...



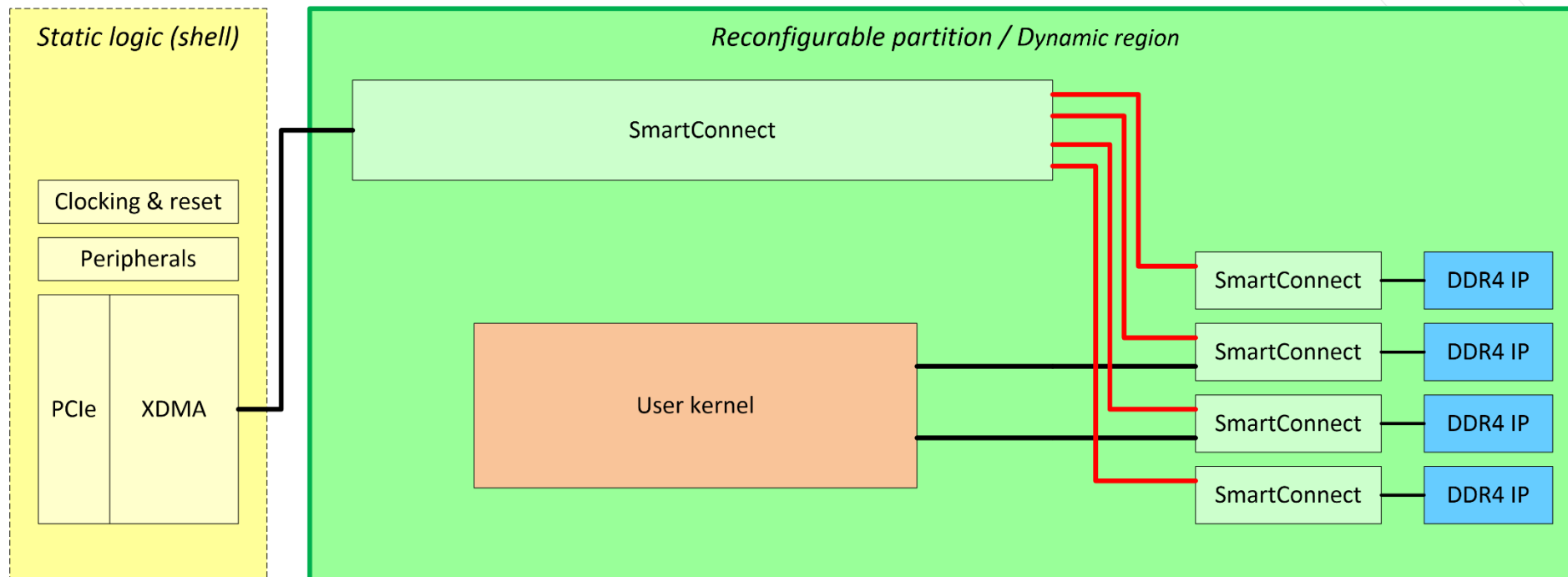
# A better way

- > Platform logic in the reconfigurable module was fixed for every kernel build...
- > ...leading to wasted FPGA area, power, and Vivado runtime when unused



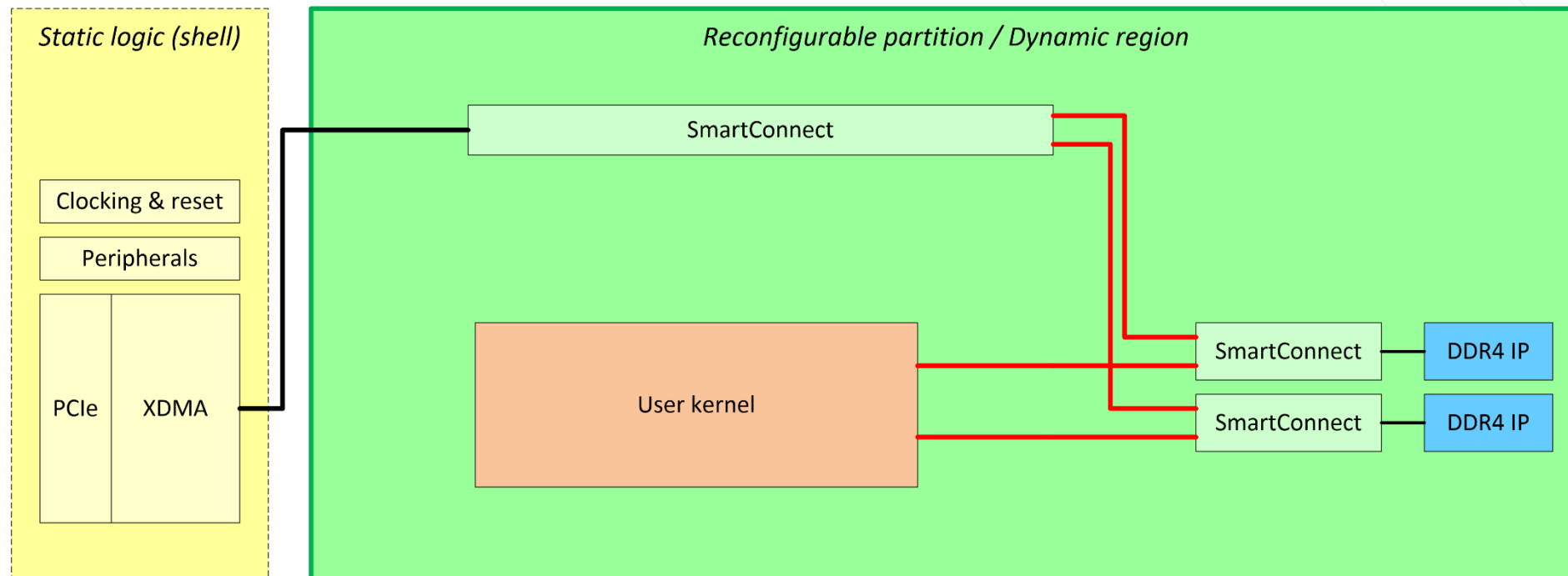
# A better way

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- > But if the entire dynamic region – not just the user kernels – could be modified by SDx...



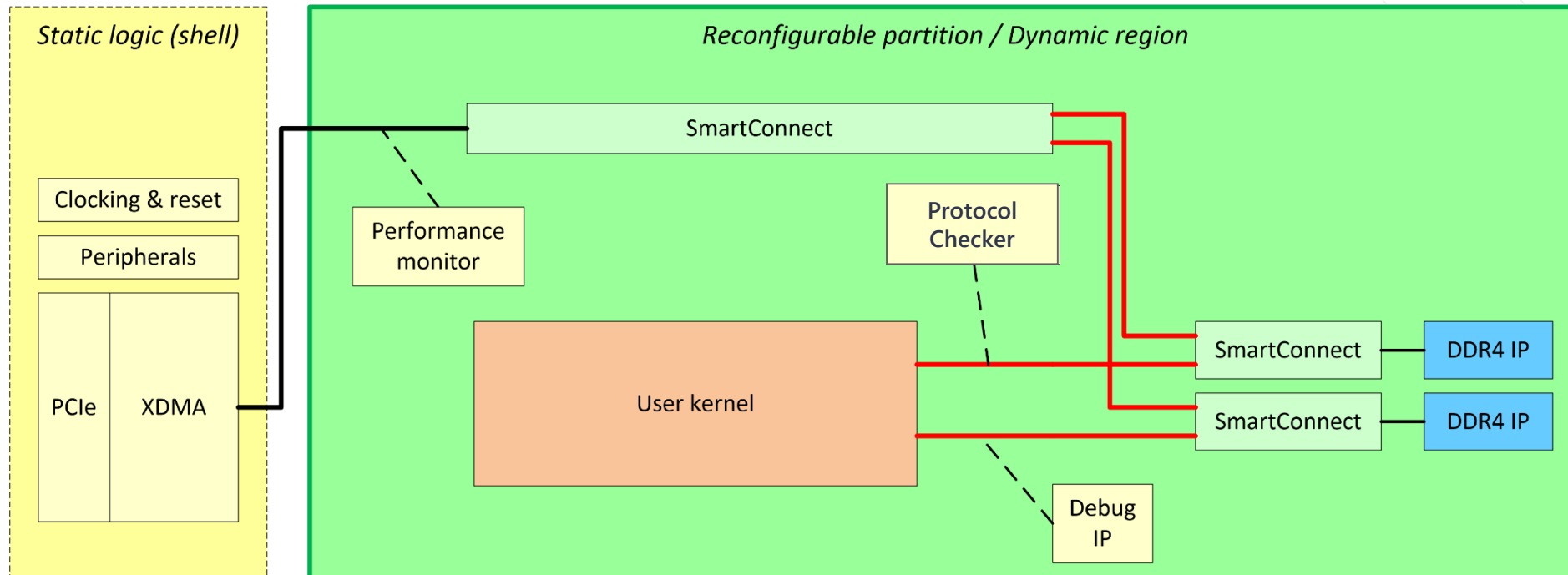
# A better way

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- > But if the entire dynamic region – not just the user kernels – could be modified by SDx...
- > ...then the platform infrastructure could best suit the kernels for every build, automatically



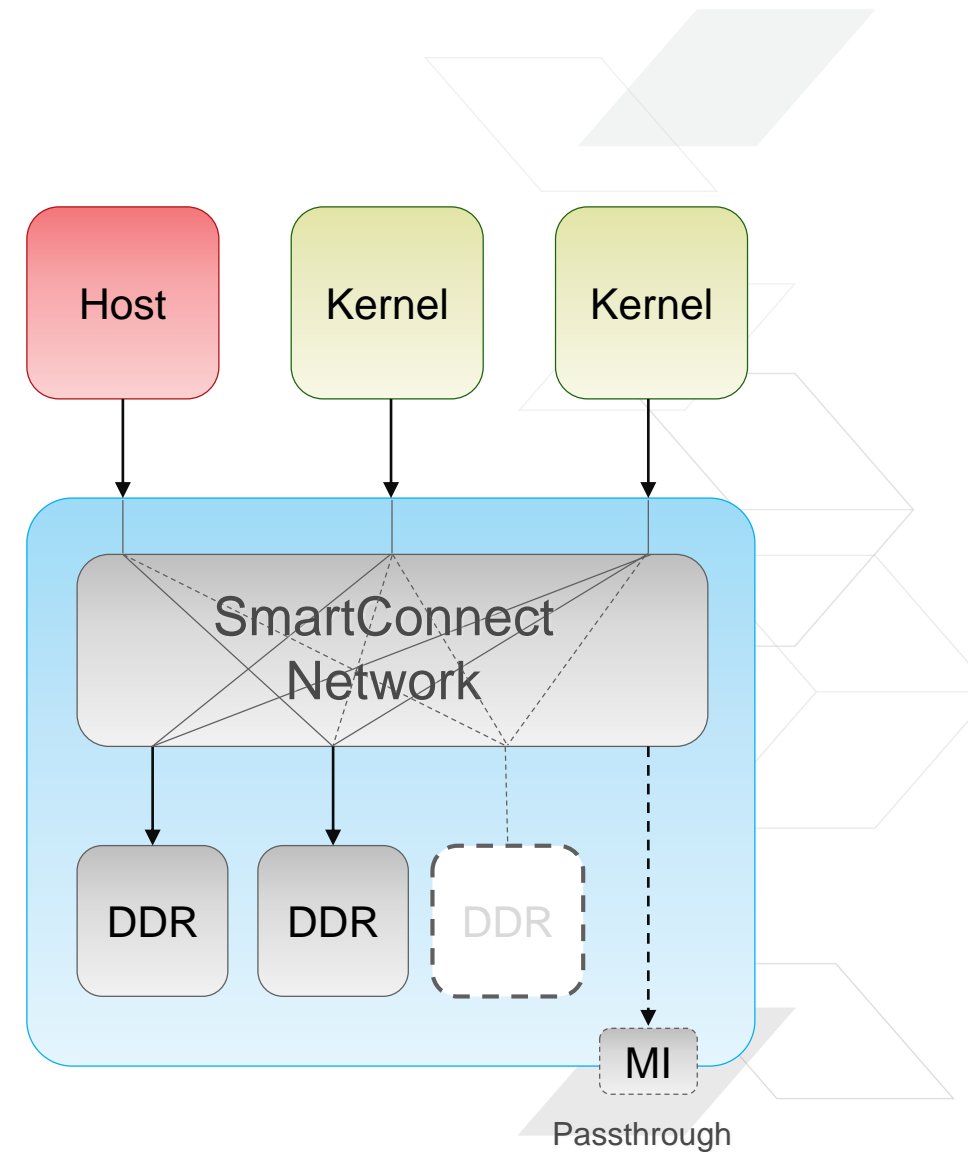
# A better way – Dynamic Platforms

- > Platform logic in the reconfigurable module was fixed for every kernel build...
- > ...leading to wasted FPGA area, power, and Vivado runtime when unused
- > But if the entire dynamic region – not just the user kernels – could be modified by SDx...
- > ...then the platform infrastructure could best suit the kernels for every build, automatically
- > *And* we'd have the framework for SDx to dynamically build up just what the user needs



# Memory subsystem Hierarchical IP

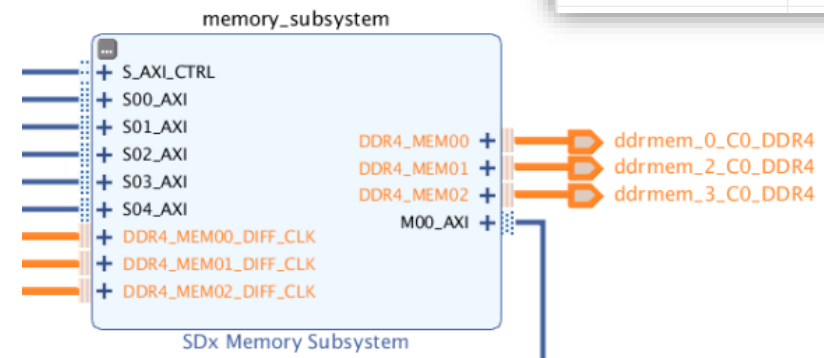
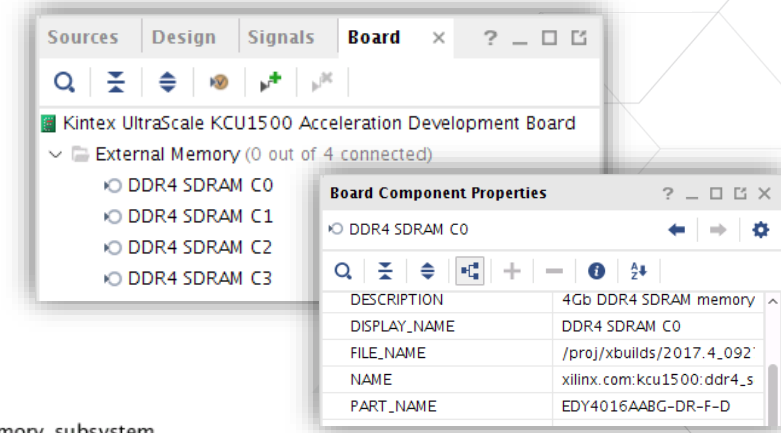
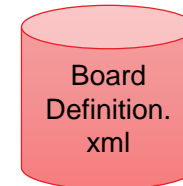
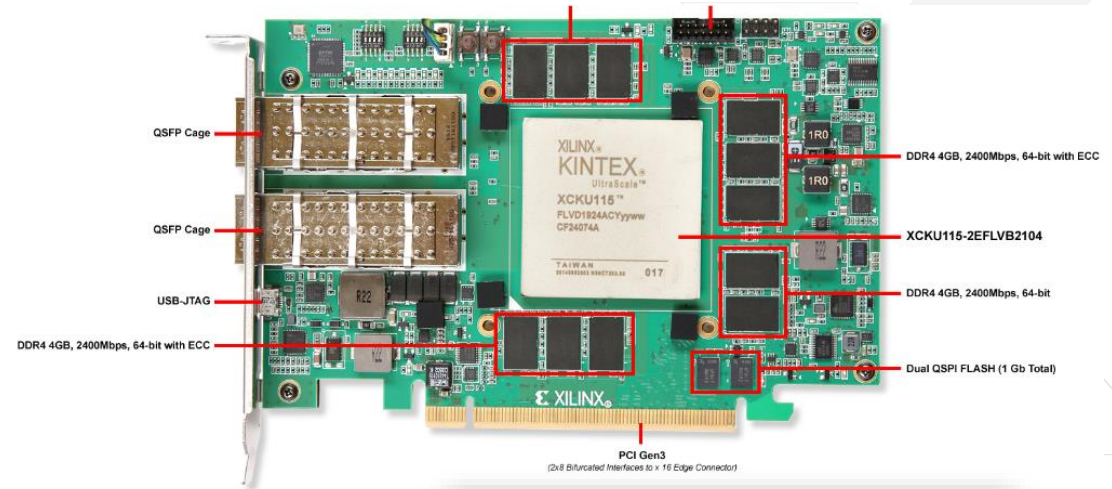
- > **Encapsulate and abstract DDR-based memory resources and associated data-interconnect instances**
  - >> Data-driven dynamic generation of interconnect and MIG instances based on application use
- > **Simplify dynamic region design**
  - >> Single IP instance versus hand constructed network of SmartConnect and MIG instances
- > **Simplify linking of kernels**
  - >> Resource based model of platform memory
  - >> Resource-Connection API hides IP-specific details of attaching Kernel's AXI interface to memory subsystem



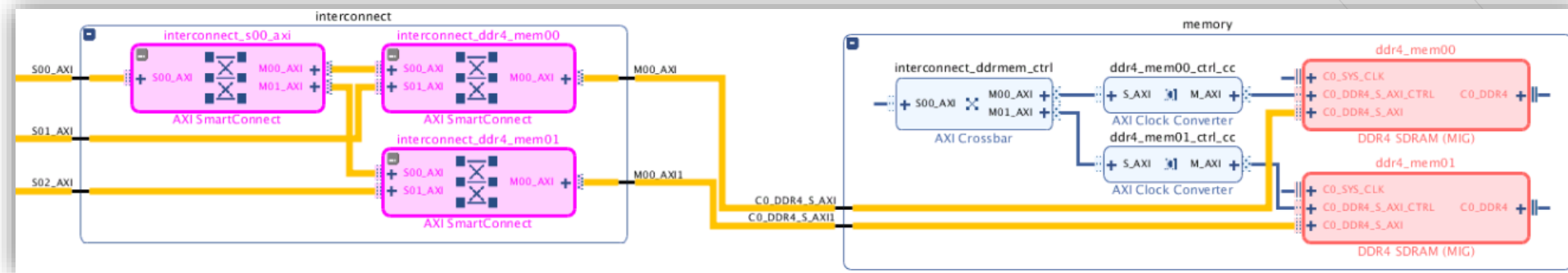
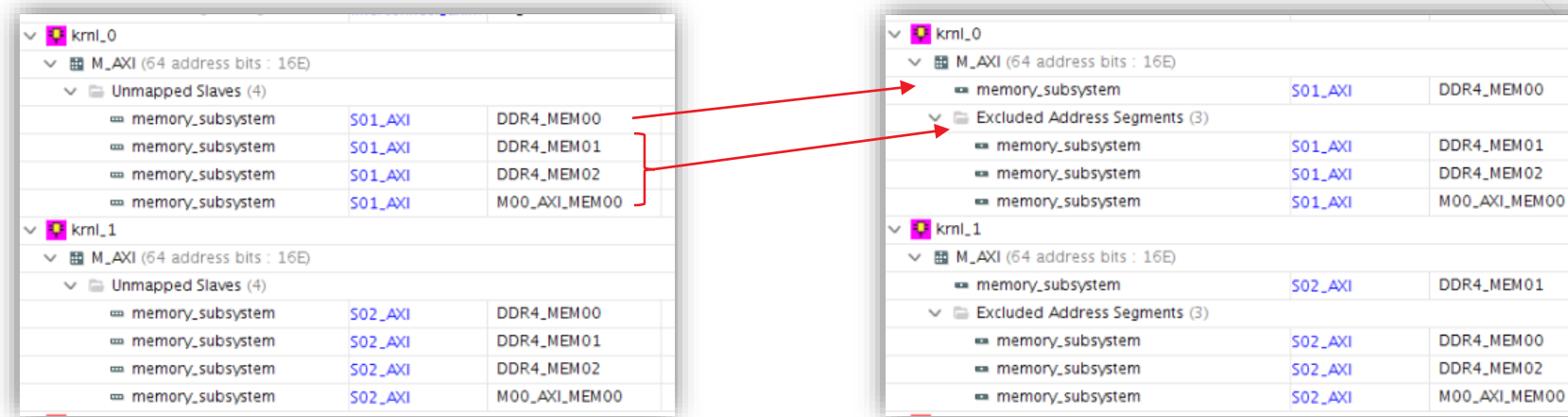


# Board-driven DDR resources

- > **What DDR resources are available in the platform?**
  - >> Avoid manual configuration specified by each DSA developer
- > **Board infrastructure provides a better experience for DSA developer**
  - >> Xilinx standard approach for board modeling
  - >> Board components document which DDR memory resources are available
  - >> Board infrastructure presets can be embedded in the board definition to provide a working configuration for the memory controller IPs

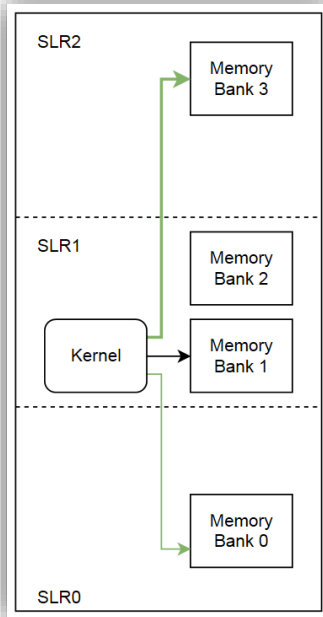
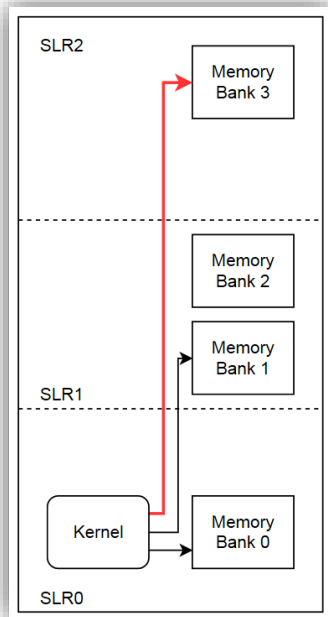


# Memory mapping and dynamic system topology



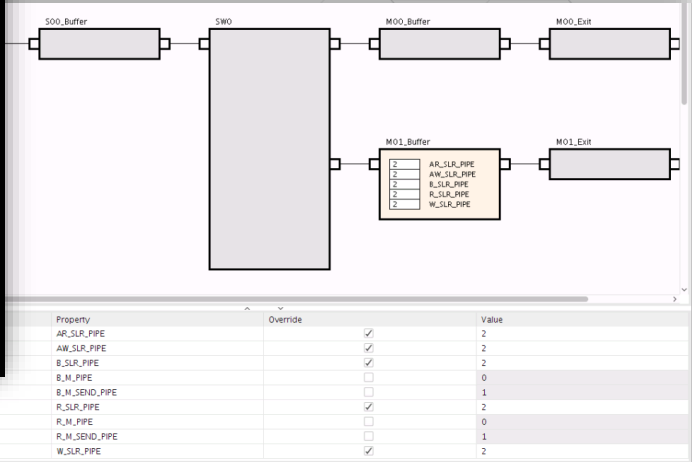
- > **AXI Interfaces advertise the set of available DDR memory resources within the memory subsystem to IPI's address editor**
  - >> Dynamic region memory controllers not actually instantiated at this point
  - >> Only create memory controllers for the memory resources that actually get mapped into Kernel's address space

# SLR automation



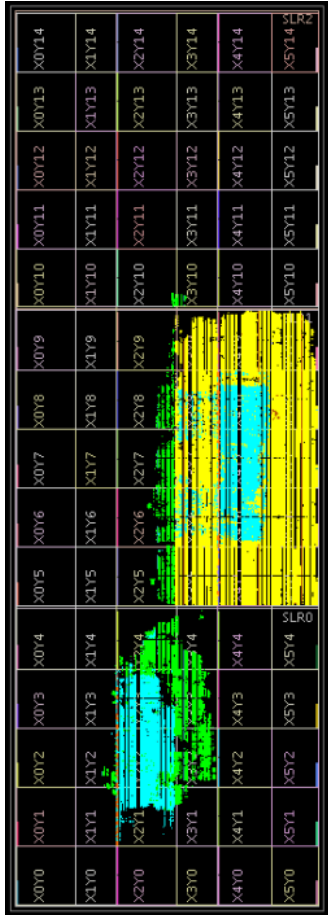
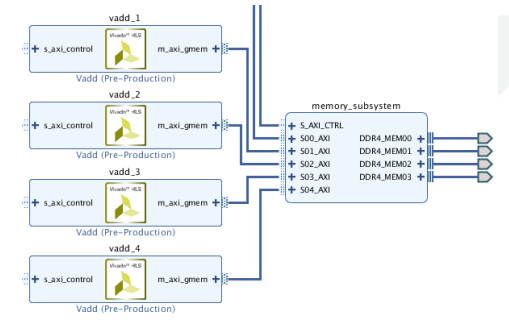
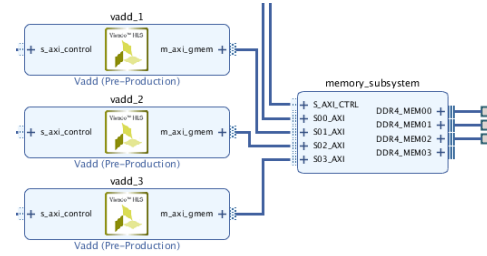
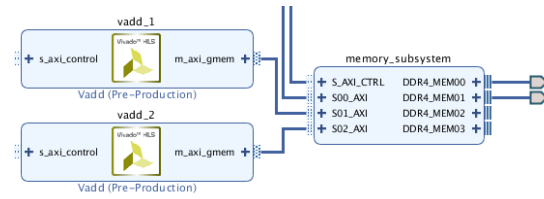
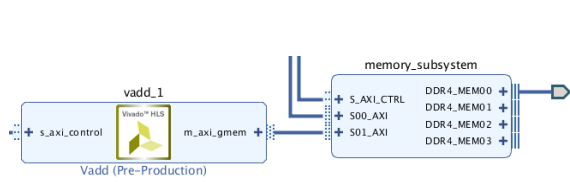
```
set_property CONFIG.SLR_ASSIGNMENTS SLR0 [get_bd_cells vadd_0]
set_property CONFIG.SLR_ASSIGNMENTS SLR1 [get_bd_cells vadd_1]
set_property CONFIG.SLR_ASSIGNMENTS SLR0 [get_bd_cells vadd_2]
```

```
# SLR-crossing PBLOCK assignments
# S00_AXI:SLR1 -> interconnect_s00_axi:SLR1
add_cells_to_pblock [get_pblocks pblock_dynamic_slr1] \
[
list \
interconnect/interconnect_s00_axi/inst/s00_nodes/s00_aw_node/inst/inst_si_handler \
interconnect/interconnect_s00_axi/inst/s00_nodes/s00_ar_node/inst/inst_si_handler \
interconnect/interconnect_s00_axi/inst/s00_nodes/s00_w_node/inst/inst_si_handler \
interconnect/interconnect_s00_axi/inst/s00_nodes/s00_r_node/inst/inst_mi_handler \
interconnect/interconnect_s00_axi/inst/s00_nodes/s00_b_node/inst/inst_mi_handler \
interconnect/interconnect_s00_axi/inst/s00_entry_pipeline \
interconnect/interconnect_s00_axi/inst/s00_axi2sc \
]
add_cells_to_pblock [get_pblocks pblock_dynamic_slr0] \
[
list \
interconnect/interconnect_s00_axi/inst/s00_nodes/s00_aw_node/inst/inst_mi_handler \
interconnect/interconnect_s00_axi/inst/s00_nodes/s00_ar_node/inst/inst_mi_handler \
interconnect/interconnect_s00_axi/inst/s00_nodes/s00_w_node/inst/inst_mi_handler \
interconnect/interconnect_s00_axi/inst/s00_nodes/s00_r_node/inst/inst_si_handler \
interconnect/interconnect_s00_axi/inst/s00_nodes/s00_b_node/inst/inst_si_handler \
]
# interconnect_s00_axi:SLR1 -> M00_AXI:SLR0
```

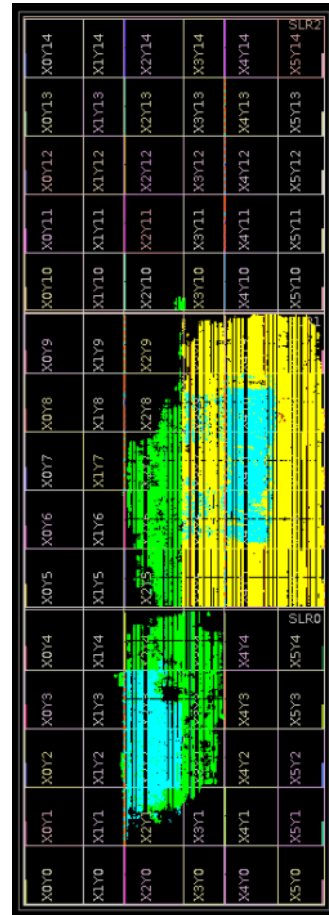


- > FaaS platforms commonly use SLR-based devices
  - >> Sometimes a kernel doesn't reside in the same SLR as the memory bank(s) it accesses
- > Memory Subsystem automates SLR crossings and IPI SLR automation provides a simple way for the user to allocate kernels to SLR
  - >> Memory Subsystem samples IPI's SLR annotations to determine how to apply SLR crossing resources
  - >> SDx 'software developer' can avoid low level details of XDC placement constraints and microarchitectural options for SLR timing pipes

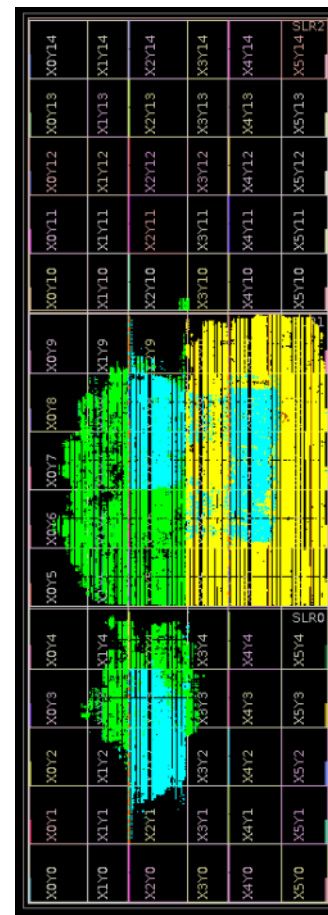
# Only build what you need



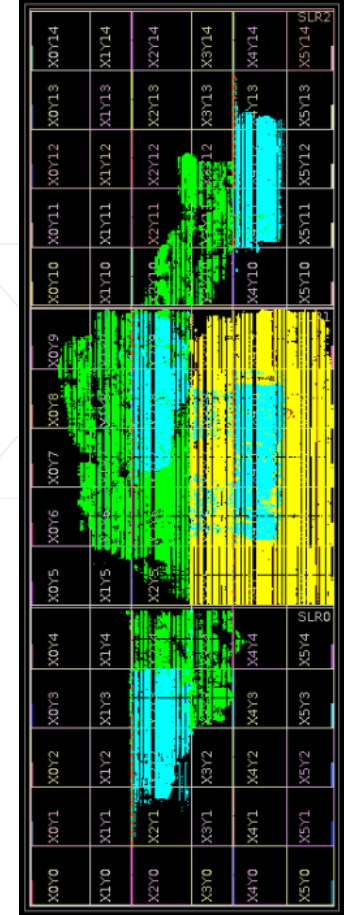
1 DDR



2 DDRs



3 DDRs



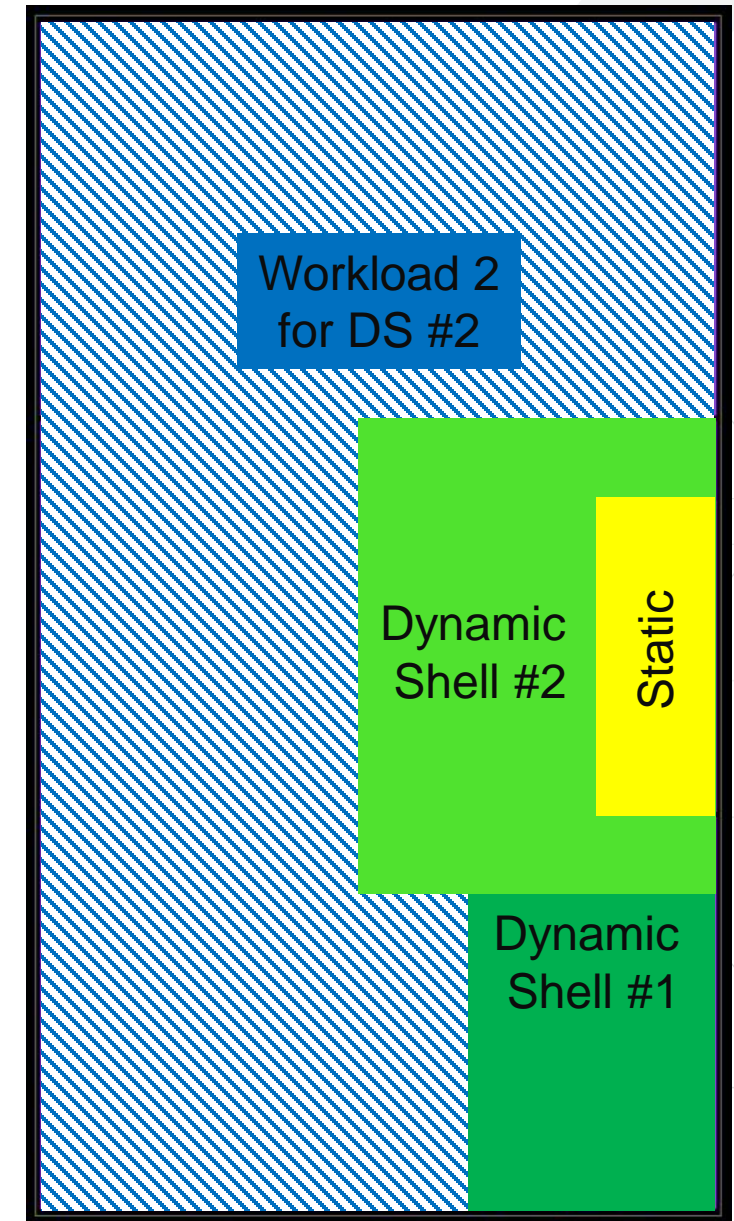
4 DDRs

# Future Enhancements for Partial Reconfiguration and Platform Design



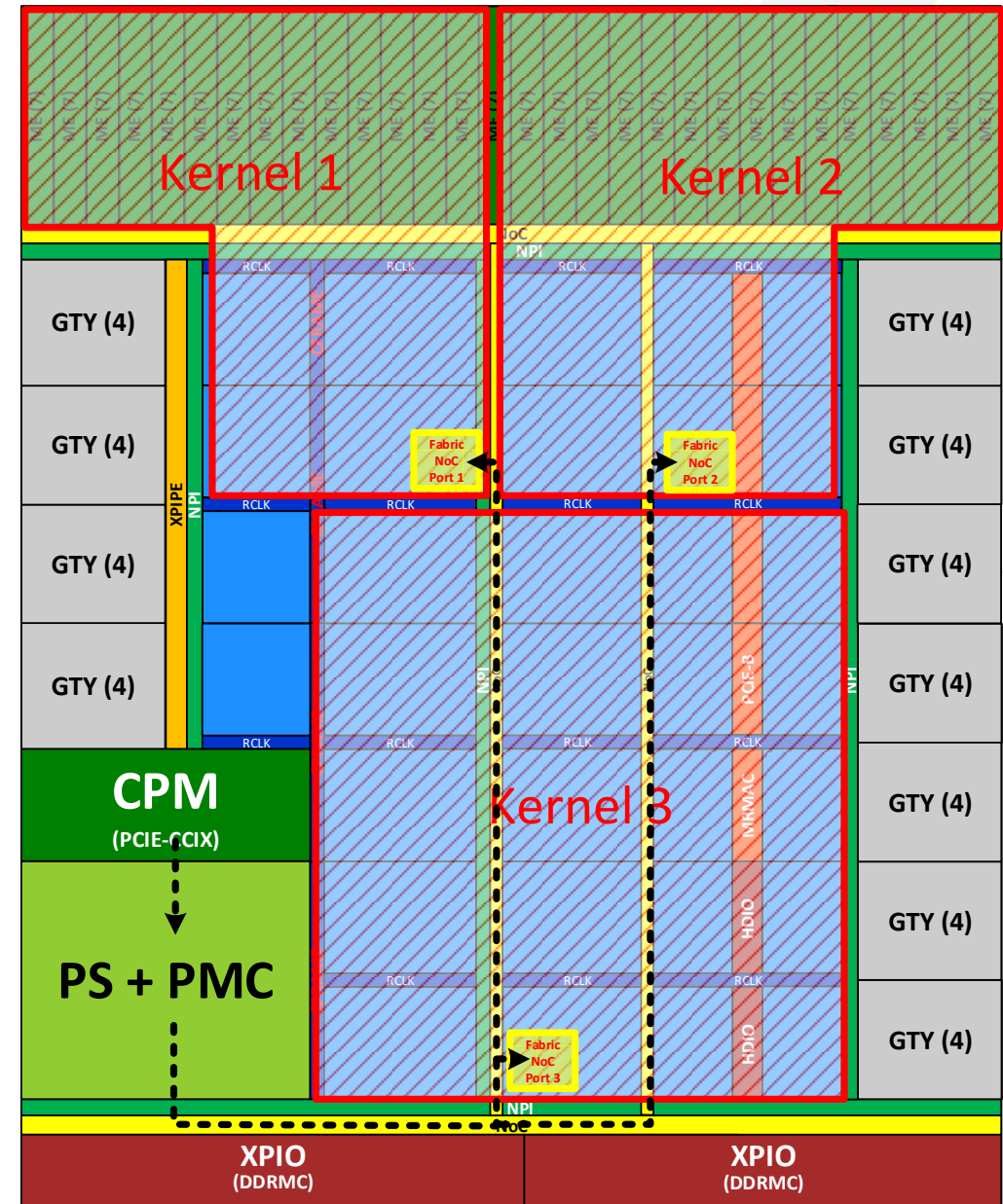
# Dynamic Shell

- > **Support multiple platforms on a single shell**
- > **Example**
  - >> Locked static design
  - >> Dynamic shell with specific features (e.g. DMA)
  - >> Multiple workloads for this shell
- > **New shell features loaded without changing static**
  - >> New dynamic shells can have:
    - Different sizes and floorplans
    - Different features
    - Different interfaces to workload space
    - Optimized for user application
  - >> Workloads must be compatible with a specific dynamic shell
    - Bitstream manager must keep track of current state



# The next generation: ACAP

- > **Hardened Memory Controllers + DDRIO**
  - >> Allows DDR memory controllers to remain active while fabric is reconfigured
  - >> Moving DDRIO out of fabric improves ease of PR floorplanning
- > **Hardened PCIe + DMA**
  - >> PCIe interface can be brought into operation with minimal programming
- > **NoC Ports in Fabric**
  - >> High bandwidth datapath to PMC for PR
- > **Configuration Performance Increase**
  - >> Max bandwidth 8X faster than Zynq US+ MPSoC (6.4GByte/sec)\*
  - >> Capable of reconfiguring 1M logic cells in under 8ms



# Summary

## Robust Silicon Technology

- > Decades of investment coupled with extensive validation of dynamic configuration solutions

## Evolution of Platform Development

- > Steadily increasing optimization for dynamic acceleration

## Exciting Future Ahead

- > Enhanced flexibility for the most efficient use of silicon



The logo consists of a red chevron pointing right, followed by the letters 'XDF' in a white, bold, sans-serif font.

XILINX  
DEVELOPER  
FORUM

